

Tree Views of a Secret in Covariant Wave Equations

中村匡 (福井県立大学 CFAAS)

2022/04/29

1 Introduction

2 3D Static Fields

Electric Field

Magnetic Field

3 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

4 Summary and Discussions

1 Introduction

2 3D Static Fields

Electric Field

Magnetic Field

3 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

4 Summary and Discussions

はじめに

- Unit System
 - $c = \hbar = 1$
 - $-1 = 2 = \frac{1}{2} = \pi = \text{some constants} = 1$
- Slide Template by Tasuku Soma (U. Tokyo)
© Copyright Tasuku Soma
- URL for this study:
https://scrapbox.io/flagments/Wave_Equations
twitter.com/gandhara16

Three sets of Basic Equations

Klein-Gordon

$$\partial_{\mu}^2 \phi = m^2 \phi$$

Maxwell

$$\partial_t \mathbf{B} + \nabla \times \mathbf{E} = 0, \text{ etc.}$$

Dirac

$$\gamma^{\mu} \partial_{\mu} \psi_D + m \psi_D = 0$$

Why look so different?

Geometric Algebra

- Geometric Algebra can show the three have identical differential operator.
- ... but Geometric Algebra is not in the standard arsenal of physicists.
- Here, the same result is obtained with a standard tool, namely, matrix manipulation.

Geometric Algebra

All you need in this talk is:

$$\hat{\gamma}^\mu \hat{\gamma}^\nu + \hat{\gamma}^\nu \hat{\gamma}^\mu = 2\hat{\eta}^{\mu\nu}$$

unit vector = algebraic object = $\hat{\gamma}^\mu$
($\eta^{\mu\nu}$: metric)

① Introduction

② 3D Static Fields

Electric Field

Magnetic Field

③ 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

④ Summary and Discussions

3D Vector Equations

Static Electric Field

$$\nabla \cdot \mathbf{E} = \rho, \quad \nabla \times \mathbf{E} = 0.$$

Static Magnetic Field

$$\nabla \times \mathbf{B} = \mathbf{J}, \quad \nabla \cdot \mathbf{B} = 0.$$

Tactics

Express with Pauli Matrices $\hat{\sigma}_j$.

Pauli Matrices

$$\hat{\sigma}_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \hat{\sigma}_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \hat{\sigma}_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

(hat mark = matrix)

$$\text{All we need is: } \frac{1}{2}(\hat{\sigma}_i \hat{\sigma}_j + \hat{\sigma}_j \hat{\sigma}_i) = \hat{1} \delta_{ij}$$

$$\hat{\sigma}_i \hat{\sigma}_j = \begin{cases} \hat{1} & \text{if } i = j \\ -\hat{\sigma}_j \hat{\sigma}_i & \text{if } i \neq j \end{cases}.$$

Electric Field Equation with Pauli Matrices

Dirac Operator

$$\hat{D} = \hat{\sigma}_1 \partial_x + \hat{\sigma}_2 \partial_y + \hat{\sigma}_3 \partial_z .$$

Electric Field

$$\hat{\mathbf{E}} = \hat{\sigma}_1 E_x + \hat{\sigma}_2 E_y + \hat{\sigma}_3 E_z .$$

Electric Field Equation

$$\begin{aligned}\hat{D}\hat{\mathbf{E}} &= (\hat{\sigma}_1\partial_x + \hat{\sigma}_2\partial_y + \hat{\sigma}_3\partial_z)(\hat{\sigma}_1E_x + \hat{\sigma}_2E_y + \hat{\sigma}_3E_z) \\ &= \hat{1}(\partial_xE_x + \partial_yE_y + \partial_zE_z) \\ &\quad + \hat{\sigma}_3\hat{\sigma}_2(\partial_zE_y - \partial_yE_z) + \hat{\sigma}_3\hat{\sigma}_1(\partial_zE_x - \partial_xE_z) \\ &\quad + \hat{\sigma}_1\hat{\sigma}_2(\partial_xE_y - \partial_yE_x)\end{aligned}$$

$$\hat{\sigma}_i\hat{\sigma}_j = \begin{cases} \hat{1} & \text{if } i = j \\ -\hat{\sigma}_j\hat{\sigma}_i & \text{if } i \neq j \end{cases}$$

$$\begin{aligned}\hat{\sigma}_1\partial_x\hat{\sigma}_1E_x &= \hat{1}\partial_xE_x \\ \hat{\sigma}_1\partial_x\hat{\sigma}_2E_y &= \hat{\sigma}_1\hat{\sigma}_2\partial_xE_y\end{aligned}$$

Vector Notation

$$\begin{aligned}\hat{D}\hat{\mathbf{E}} &= (\hat{\sigma}_1\partial_x + \hat{\sigma}_2\partial_y + \hat{\sigma}_3\partial_z)(\hat{\sigma}_1E_x + \hat{\sigma}_2E_y + \hat{\sigma}_3E_z) \\ &= \hat{1}(\partial_xE_x + \partial_yE_y + \partial_zE_z) \\ &\quad + \hat{\sigma}_3\hat{\sigma}_2(\partial_zE_y - \partial_yE_z) + \hat{\sigma}_3\hat{\sigma}_1(\partial_zE_x - \partial_xE_z) \\ &\quad + \hat{\sigma}_1\hat{\sigma}_2(\partial_xE_y - \partial_yE_x) \\ &= \hat{1}\rho\end{aligned}$$

$$\hat{D}\hat{\mathbf{E}} = \begin{cases} \nabla \cdot \mathbf{E} = \rho & (i = j) \\ \nabla \times \mathbf{E} = 0 & (i \neq j) \end{cases} \rightarrow \mathbf{E} = \nabla\phi$$

$\hat{\sigma}$ as Unit Vectors

$$\hat{D} = \hat{\sigma}_1 \partial_x + \hat{\sigma}_2 \partial_y + \hat{\sigma}_3 \partial_z$$

$$\hat{\mathbf{E}} = \hat{\sigma}_1 E_x + \hat{\sigma}_2 E_y + \hat{\sigma}_3 E_z$$

$$\hat{D}\hat{\mathbf{E}} = (\hat{\sigma}_1 \partial_x + \hat{\sigma}_2 \partial_y + \hat{\sigma}_3 \partial_z)(\hat{\sigma}_1 E_x + \hat{\sigma}_2 E_y + \hat{\sigma}_3 E_z)$$

$$= \hat{1}(\partial_x E_x + \partial_y E_y + \partial_z E_z)$$

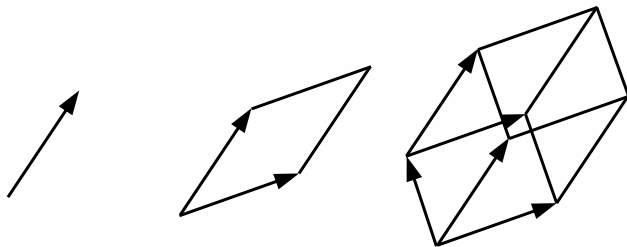
$$+ \hat{\sigma}_3 \hat{\sigma}_2 (\partial_z E_y - \partial_y E_z) + \hat{\sigma}_3 \hat{\sigma}_1 (\partial_z E_x - \partial_x E_z)$$

$$+ \hat{\sigma}_1 \hat{\sigma}_2 (\partial_x E_y - \partial_y E_x)$$

$$\Rightarrow \nabla \cdot \mathbf{E} + \nabla \times \mathbf{E}$$

$$\hat{\sigma}_i \Leftrightarrow \mathbf{e}_i, \quad \hat{\sigma}_i \hat{\sigma}_j \Leftrightarrow \begin{cases} 1 & (i = j) \\ \mathbf{e}_i \times \mathbf{e}_k & (i \neq j) \end{cases}$$

Multi Vectors



$$\hat{\sigma}_i \Leftrightarrow \mathbf{e}_i \quad \hat{\sigma}_i \hat{\sigma}_j \Leftrightarrow \mathbf{e}_i \times \mathbf{e}_j \quad \hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k \Leftrightarrow \mathbf{e}_k \cdot (\mathbf{e}_i \times \mathbf{e}_j)$$

grade	0	1	2	3
unit	$\hat{1}$	$\hat{\sigma}_i$	$\hat{\sigma}_i \hat{\sigma}_j$	$\hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k$
object	point	line	surface	volume
components	1	3	3	1

1 Introduction

2 3D Static Fields

Electric Field

Magnetic Field

3 4D Wave Fields

3D to 4D

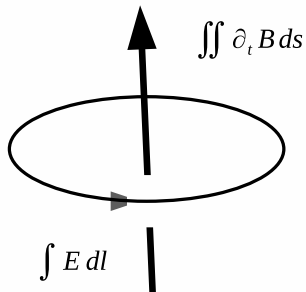
Vector Equations

Spinor Equation

4 Summary and Discussions

Magnetic Field with Pauli Matrices

$$\hat{\mathbf{B}} = \hat{\sigma}_2 \hat{\sigma}_3 B_x + \hat{\sigma}_3 \hat{\sigma}_1 B_y + \hat{\sigma}_1 \hat{\sigma}_2 B_z$$



Magnetic Field Equation

Dirac Operator

$$\hat{D} = \hat{\sigma}_1 \partial_x + \hat{\sigma}_2 \partial_y + \hat{\sigma}_3 \partial_z .$$

Magnetic Field

$$\hat{\mathbf{B}} = \hat{\sigma}_2 \hat{\sigma}_3 B_x + \hat{\sigma}_3 \hat{\sigma}_1 B_y + \hat{\sigma}_1 \hat{\sigma}_2 B_z$$

$$\begin{aligned} \hat{D} \hat{\mathbf{B}} &= (\hat{\sigma}_1 \partial_x + \hat{\sigma}_2 \partial_y + \hat{\sigma}_3 \partial_z) (\hat{\sigma}_2 \hat{\sigma}_3 B_x + \hat{\sigma}_3 \hat{\sigma}_1 B_y + \hat{\sigma}_1 \hat{\sigma}_2 B_z) \\ &= \hat{\sigma}_1 (\partial_z B_y - \partial_y B_z) + \hat{\sigma}_2 (\partial_z B_x - \partial_x B_z) \\ &\quad + \hat{\sigma}_3 (\partial_x B_y - \partial_y B_x) \\ &\quad + \hat{\sigma}_1 \hat{\sigma}_2 \hat{\sigma}_3 (\partial_x B_x + \partial_y B_y + \partial_z B_z) \\ &\Rightarrow \nabla \times \mathbf{B} + \nabla \cdot \mathbf{B} \end{aligned}$$

Electric and Magnetic Fields

$$\begin{aligned}\hat{D}\hat{\mathbf{E}} &= (\hat{\sigma}_1\partial_x + \hat{\sigma}_2\partial_y + \hat{\sigma}_3\partial_z)(\hat{\sigma}_1E_x + \hat{\sigma}_2E_y + \hat{\sigma}_3E_z) \\ &= \hat{1}(\partial_xE_x + \partial_yE_y + \partial_zE_z) \\ &\quad + \hat{\sigma}_3\hat{\sigma}_2(\partial_zE_y - \partial_yE_z) + \hat{\sigma}_3\hat{\sigma}_1(\partial_zE_x - \partial_xE_z) \\ &\quad + \hat{\sigma}_1\hat{\sigma}_2(\partial_xE_y - \partial_yE_x) \\ &\Rightarrow \nabla \cdot \mathbf{E} + \nabla \times \mathbf{E}\end{aligned}$$

$$\begin{aligned}\hat{D}\hat{\mathbf{B}} &= (\hat{\sigma}_1\partial_x + \hat{\sigma}_2\partial_y + \hat{\sigma}_3\partial_z)(\hat{\sigma}_2\hat{\sigma}_3B_x + \hat{\sigma}_3\hat{\sigma}_1B_y + \hat{\sigma}_1\hat{\sigma}_2B_z) \\ &= \hat{\sigma}_1(\partial_zB_y - \partial_yB_z) + \hat{\sigma}_2(\partial_zB_x - \partial_xB_z) \\ &\quad + \hat{\sigma}_3(\partial_xB_y - \partial_yB_x) \\ &\quad + \hat{\sigma}_1\hat{\sigma}_2\hat{\sigma}_3(\partial_xB_x + \partial_yB_y + \partial_zB_z) \\ &\Rightarrow \nabla \times \mathbf{B} + \nabla \cdot \mathbf{B}\end{aligned}$$

Operator and Operand

Electric Field line: $\mathbf{E} = \hat{\sigma}_i E_i$

$$\hat{D}\hat{\mathbf{E}} = (\hat{\sigma}_i D_i)(\hat{\sigma}_j E_j) = \hat{1} \nabla \cdot \mathbf{E} + \hat{\sigma}_i \hat{\sigma}_j \epsilon_{kij} [\nabla \times \mathbf{E}]_k$$

Magnetic Field surface: $\mathbf{B} = \hat{\sigma}_i \hat{\sigma}_j \epsilon_{kij} B_k$

$$\hat{D}\hat{\mathbf{B}} = (\hat{\sigma}_i D_i)(\hat{\sigma}_i \hat{\sigma}_j B_j) = \hat{\sigma}_i [\nabla \times \mathbf{B}]_i + \hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k \nabla \cdot \mathbf{B}$$

grade	0	1	2	3
unit	$\hat{1}$	$\hat{\sigma}_i$	$\hat{\sigma}_i \hat{\sigma}_j$	$\hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k$
object	point	line	surface	volume
components	1	3	3	1
elec.	$\nabla \cdot \mathbf{E}$	\mathbf{E}	$\nabla \times \mathbf{E}$	
mag.		$\nabla \times \mathbf{B}$	\mathbf{B}	$\nabla \cdot \mathbf{B}$

① Introduction

② 3D Static Fields

Electric Field

Magnetic Field

③ 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

④ Summary and Discussions

4D Vectors

- Unit Vector: $\hat{\sigma}_i \Rightarrow \hat{\gamma}^\mu$
- Operator: $\hat{D} = \hat{\gamma}^t \partial_t + \hat{\gamma}^x \partial_x + \hat{\gamma}^y \partial_y + \hat{\gamma}^z \partial_z$

$$\hat{\gamma}^\mu \hat{\gamma}^\nu + \hat{\gamma}^\nu \hat{\gamma}^\mu = 2\hat{\eta}^{\mu\nu}$$

($\hat{\eta}$: metric)

3D \Rightarrow 4D

grade	0	1	2	3
unit	$\hat{1}$	$\hat{\sigma}_i$	$\hat{\sigma}_i \hat{\sigma}_j$	$\hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k$
object	point	line	surface	volume
components	1	3	3	1
elec. mag.	$\nabla \cdot \mathbf{E}$	\mathbf{E} $\nabla \times \mathbf{B}$	$\nabla \times \mathbf{E}$ \mathbf{B}	$\nabla \cdot \mathbf{B}$

grade	0	1	2	3	4
unit	$\hat{1}$	$\hat{\gamma}^\mu$	$\hat{\gamma}^\mu \hat{\gamma}^\nu$	$\hat{\gamma}^\mu \hat{\gamma}^\nu \hat{\gamma}^\alpha$	$\hat{\gamma}^\mu \hat{\gamma}^\nu \hat{\gamma}^\alpha \hat{\gamma}^\beta$
object	point	line	surface	3-volume	4-volume
components	1	4	6	4	1
line-type	$\hat{\delta}\hat{\mathcal{V}}$	$\hat{\mathcal{V}}$	$\hat{d}\hat{\mathcal{V}}$		
surface-type		$\hat{\delta}\hat{\mathcal{F}}$	$\hat{\mathcal{F}}$	$\hat{d}\hat{\mathcal{F}}$	

Vector Equations: Static 3D EM Fields

- Operator:

$$\hat{D} = \hat{\sigma}_x \partial_x + \hat{\sigma}_y \partial_y + \hat{\sigma}_z \partial_z$$

- Operand:

- Line \Rightarrow Electric Field

$$\hat{\mathbf{E}} = \hat{\sigma}_1 E_x + \hat{\sigma}_2 E_y + \hat{\sigma}_3 E_z$$

- Surface \Rightarrow Magnetic Field

$$\hat{\mathbf{B}} = \hat{\sigma}_2 \hat{\sigma}_3 B_x + \hat{\sigma}_3 \hat{\sigma}_1 B_y + \hat{\sigma}_1 \hat{\sigma}_2 B_z$$

Vector Equations: 4D

- Operator:

$$\hat{D} = \hat{\gamma}^t \partial_t + \hat{\gamma}^x \partial_x + \hat{\gamma}^y \partial_y - + \hat{\gamma}^z \partial_z$$

- Operand:

- Line \Rightarrow Klein-Gordon

$$\hat{\mathcal{V}} = \hat{\gamma}^t \hat{\mathcal{V}}_t + \hat{\gamma}^x \hat{\mathcal{V}}_x + \hat{\gamma}^y \hat{\mathcal{V}}_y - + \hat{\gamma}^z \hat{\mathcal{V}}_z$$

- Surface \Rightarrow Maxwell

$$\begin{aligned} \hat{\mathcal{F}} = & \hat{\gamma}^t \hat{\gamma}^x E_x + \hat{\gamma}^t \hat{\gamma}^y E_x + \hat{\gamma}^t \hat{\gamma}^z E_z \\ & + \hat{\gamma}^y \hat{\gamma}^z B_x + \hat{\gamma}^z \hat{\gamma}^x B_y + \hat{\gamma}^x \hat{\gamma}^y B_z \end{aligned}$$

The Klein-Gordon Equation

$$\hat{\mathcal{V}} = \hat{\gamma}^\mu \partial_\mu \phi$$

$$\begin{aligned}\hat{D}\hat{\mathcal{V}} &= \hat{\gamma}^t \hat{\gamma}^x (V_{t,x} - V_{x,t}) + \hat{\gamma}^t \hat{\gamma}^y (V_{t,y} - V_{y,t}) \\ &\quad + \hat{\gamma}^t \hat{\gamma}^z (V_{t,z} - V_{z,t}) + \hat{\gamma}^x \hat{\gamma}^y (V_{x,y} - V_{y,x}) \\ &\quad + \hat{\gamma}^z \hat{\gamma}^x (V_{z,x} - V_{x,z}) + \hat{\gamma}^x \hat{\gamma}^y (V_{x,y} - V_{y,x}) \\ &= \hat{1} (V_{t,t} + V_{x,x} + V_{y,y} + V_{z,z}) \\ &\equiv \hat{\delta}\hat{\mathcal{V}} + \hat{d}\hat{\mathcal{V}}\end{aligned}$$

$$\hat{D}\hat{\mathcal{V}} = \begin{cases} \hat{\delta}\hat{\mathcal{V}} = 0 & \rightarrow \hat{\mathcal{V}} = \nabla \cdot \phi \\ \hat{d}\hat{\mathcal{V}} = m^2 \phi \end{cases}$$

Electrostatic Field

$$\mathbf{E} = \nabla \cdot \phi$$

$$\begin{aligned}\hat{D}\hat{\mathbf{E}} &= +\hat{\sigma}_3\hat{\sigma}_2(\partial_z E_y - \partial_y E_z) + \hat{\sigma}_3\hat{\sigma}_1(\partial_z E_x - \partial_x E_z) \\ &\quad + \hat{\sigma}_1\hat{\sigma}_2(\partial_x E_y - \partial_y E_x) \\ &\quad + \hat{1}(\partial_x E_x + \partial_y E_y + \partial_z E_z) \\ &= \hat{1}\rho\end{aligned}$$

$$\hat{D}\hat{\mathbf{E}} = \begin{cases} \nabla \times \mathbf{E} = 0 & (i \neq j) \\ \nabla \cdot \mathbf{E} = \rho & (i = j) \end{cases} \rightarrow \mathbf{E} = \nabla\phi$$

Line-type: The Klein-Gordon Equation

$$\hat{D}\hat{\mathcal{V}} = (\hat{\delta} + \hat{d})\hat{\mathcal{V}} = m^2\phi$$

components	1	4	6	4	1
object	point	line	surface	3-volume	4-volume
line-type	$\hat{\delta}\hat{\mathcal{V}}$	$\hat{\mathcal{V}}$	$\hat{d}\hat{\mathcal{V}}$		
surface-type		$\hat{\delta}\hat{\mathcal{F}}$	$\hat{\mathcal{F}}$	$\hat{d}\hat{\mathcal{F}}$	

$$\hat{\mathcal{V}} = \hat{y}^\mu \partial_\mu \phi$$

Surface-type: Maxwell Equations

$$\hat{\mathcal{F}} = \hat{\gamma}^\mu \hat{\gamma}^\nu F_{\mu\nu} : \quad F_{0i} = E_i, \quad F_{ij} = \epsilon_{kij} B_k$$

$$\hat{\gamma}^t \partial_t (\hat{\gamma}^t \hat{\gamma}^x E_x) = \hat{\gamma}^x \partial_t E_x, \quad \hat{\gamma}^x \partial_x (\hat{\gamma}^t \hat{\gamma}^x E_x) = \hat{\gamma}^t \partial_x E_x,$$

$$\hat{\gamma}_y \partial_y (\hat{\gamma}^t \hat{\gamma}^x E_x) = \hat{\gamma}^t \hat{\gamma}^x \partial_y E_x,$$

$$\hat{\gamma}^t \partial_t (\hat{\gamma}^y \hat{\gamma}^z B_x) = \hat{\omega} \hat{\gamma}^x \partial_x B_x, \quad \hat{\gamma}^x \partial_x (\hat{\gamma}^y \hat{\gamma}^z B_x) = \hat{\omega} \hat{\gamma}^t \partial_x B_x,$$

$$\hat{\gamma}_y \partial_y (\hat{\gamma}^t \hat{\gamma}^x B_x) = \hat{\omega} \hat{\gamma}^x \partial_y B_x.$$

Maxwell Equations

components	1	4	6	4	1
object	point	line	surface	3-volume	4-volume
line-type	$\hat{\delta}\hat{\mathcal{V}}$	$\hat{\mathcal{V}}$	$\hat{d}\hat{\mathcal{V}}$		
surface-type		$\hat{\delta}\hat{\mathcal{F}}$	$\hat{\mathcal{F}}$	$\hat{d}\hat{\mathcal{F}}$	

$$\hat{D}\hat{\mathcal{F}} = \hat{\delta}\hat{\mathcal{F}} + \hat{d}\hat{\mathcal{F}} = J_{\mu}\hat{\gamma}^{\mu} \equiv \hat{\mathcal{J}} \quad (1)$$

$$\hat{\delta}\hat{\mathcal{F}} = \hat{\mathcal{J}} \quad \rightarrow \quad \nabla \cdot \mathbf{E} = \rho, \quad \partial_t \mathbf{E} + \nabla \times \mathbf{B} = \mathbf{J}$$

$$\begin{aligned} \hat{d}\hat{\mathcal{F}} = 0 &\quad \rightarrow \quad \nabla \cdot \mathbf{B} = 0, \quad \partial_t \mathbf{B} + \nabla \times \mathbf{E} = 0 \\ &\quad \rightarrow \quad \nabla \times \mathbf{A} = \mathbf{B} \end{aligned}$$

1 Introduction

2 3D Static Fields

Electric Field

Magnetic Field

3 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

4 Summary and Discussions

EM Fields in Matrix Form

$$\hat{\mathcal{F}} = \hat{\gamma}^t \hat{\gamma}^x E_x + \hat{\gamma}^t \hat{\gamma}^y E_y + \hat{\gamma}^t \hat{\gamma}^z E_z \\ + \hat{\gamma}^y \hat{\gamma}^z B_x + \hat{\gamma}^z \hat{\gamma}^x B_y + \hat{\gamma}^x \hat{\gamma}^y B_z$$

with Dirac Basis

$$\hat{\mathcal{F}} = \begin{pmatrix} B_z & B_x - iB_y & iE_z & iE_x + E_y \\ B_x + iB_y & -B_z & iE_x - E_y & -iE_z \\ iE_z & iE_x + E_y & B_z & B_x - iB_y \\ iE_x - E_y & -iE_z & B_x + iB_y & -B_z \end{pmatrix}$$

Dirac Form

$$\hat{\mathcal{F}} = \begin{pmatrix} B_z & B_x - iB_y & iE_z & iE_x + E_y \\ B_x + iB_y & -B_z & iE_x - E_y & -iE_z \\ iE_z & iE_x + E_y & B_z & B_x - iB_y \\ iE_x - E_y & -iE_z & B_x + iB_y & B_z \end{pmatrix}$$



$$\hat{\psi}_{EM} = \begin{pmatrix} B_z \\ B_x + iB_y \\ iE_z \\ iE_x - E_y \end{pmatrix}$$

Maxwell Equations in Dirac Form

Operator: Derivative

$$\hat{D} = \hat{\gamma}^t \partial_t + \hat{\gamma}^x \partial_x + \hat{\gamma}^y \partial_y + \hat{\gamma}^z \partial_z$$

Operand: Wave Fields

$$\hat{\psi}_{EM} = \begin{pmatrix} B_z \\ B_x + iB_y \\ iE_z \\ iE_x - E_y \end{pmatrix}$$

Maxwell Eqs. in Dirac Form

$$\hat{D}\hat{\psi}_{EM} = \hat{\gamma}^\mu \partial_\mu \hat{\psi}_{EM} = \hat{J}$$

Maxwell Form

Dirac Wave Function

$$\hat{\psi}_{EM} = \begin{pmatrix} B_z \\ B_x + iB_y \\ iE_z \\ iE_x - E_y \end{pmatrix} \Rightarrow \hat{\psi}_D = \begin{pmatrix} i\alpha_0 + \beta_z \\ \beta_x + i\beta_y \\ \alpha_\omega + i\varepsilon_z \\ i\varepsilon_x - \varepsilon_y \end{pmatrix}$$

Dirac Equation in Maxwell Form (massless)

$$\begin{aligned} \partial_t \alpha_0 + \nabla \cdot \boldsymbol{\varepsilon} &= 0, & \nabla \alpha_0 + \partial_t \boldsymbol{\varepsilon} - \nabla \times \boldsymbol{\beta} &= 0 \\ \partial_t \alpha_\omega + \nabla \cdot \boldsymbol{\beta} &= 0, & \nabla \alpha_\omega + \partial_t \boldsymbol{\beta} + \nabla \times \boldsymbol{\varepsilon} &= 0 \end{aligned}$$

Wave Equations

- Operator:

$$\hat{D} = \hat{\gamma}^t \partial_t + \hat{\gamma}^x \partial_x + \hat{\gamma}^y \partial_y + \hat{\gamma}^z \partial_z$$

- Operand:

Translation: vector

- **Line**

$$\text{Klein-Gordon: } \partial_t^2 \phi - \partial_x^2 \phi - \partial_y^2 \phi - \partial_z^2 \phi$$

- **Surface**

$$\text{Maxwell: } \partial_t \mathbf{B} + \nabla \times \mathbf{E}, \text{ etc.}$$

Rotation: rotor

- **Spin**

$$\text{Dirac: } \gamma^\mu \partial_\mu \psi_D$$

① Introduction

② 3D Static Fields

Electric Field

Magnetic Field

③ 4D Wave Fields

3D to 4D

Vector Equations

Spinor Equation

④ Summary and Discussions

Summary

- 3D static fields are good exercise for 4D fields.
- The Klein-Gordon, Maxwell, and Dirac equations are expressed in similar forms.
 - Klein-Gordon, Maxwell \Rightarrow Dirac Matrices
 - Dirac \Rightarrow Vector Analysis
- Differential Operators are identical.
- Operand (wave field) makes difference, not Operators.

Equation	Field	Matrix	Vector Analysis
Klein-Gordon	line	$D\mathcal{V} = m\phi$	$\nabla^2\phi = m^2\phi$
Maxwell	surface	$D\mathcal{F} = \mathcal{J}$	$\partial_t\mathbf{E} + \nabla \times \mathbf{B} = \mathbf{J}$, etc.
Dirac	rotation	$D\psi_D = m\psi_D$	$\nabla \cdot \alpha_0 + \partial_t\epsilon - \nabla \times \beta = m\epsilon$, etc.

Geometric Algebra

Vector Calculations

- Component Calculation
- Quaternion (Hamilton)
- Exterior Algebra (Grassmann)
- Clifford Algebra (Clifford)
- Vector Analysis (Gibbs, Heaviside)
- Differential Form (Cartan)
- Geometric Algebra (Hestenes)

Algebraic Relation for Geometric Algebra

$$\hat{\gamma}^{\mu} \hat{\gamma}^{\nu} + \hat{\gamma}^{\nu} \hat{\gamma}^{\mu} = 2\hat{\eta}^{\mu\nu}$$

3D \Rightarrow 4D

grade	0	1	2	3
unit	$\hat{1}$	$\hat{\sigma}_i$	$\hat{\sigma}_i \hat{\sigma}_j$	$\hat{\sigma}_i \hat{\sigma}_j \hat{\sigma}_k$
object	point	line	surface	volume
components	1	3	3	1
elec. mag.	$\nabla \cdot \mathbf{E}$	\mathbf{E} $\nabla \times \mathbf{B}$	$\nabla \times \mathbf{E}$ \mathbf{B}	$\nabla \cdot \mathbf{B}$

grade	0	1	2	3	4
unit	$\hat{1}$	$\hat{\gamma}^\mu$	$\hat{\gamma}^\mu \hat{\gamma}^\nu$	$\hat{\gamma}^\mu \hat{\gamma}^\nu \hat{\gamma}^\alpha$	$\hat{\gamma}^\mu \hat{\gamma}^\nu \hat{\gamma}^\alpha \hat{\gamma}^\beta$
object	point	line	surface	3-volume	4-volume
components	1	4	6	4	1
line-type	$\hat{\delta}\hat{\mathcal{V}}$	$\hat{\mathcal{V}}$	$\hat{d}\hat{\mathcal{V}}$		
surface-type		$\hat{\delta}\hat{\mathcal{F}}$	$\hat{\mathcal{F}}$	$\hat{d}\hat{\mathcal{F}}$	

Structured Data

- Non-structured:

```
DayOfWeek := 3 ;  
ThreeDaysLater := DayOfWeek + 3 ;  
if(ThreeDaysLater > 7)...
```

- Structured:

```
type DofW: {sun,mon,tue,wed,ths,fri,sat} ;  
var DayOfWeek: DofW ;  
  
DayOfWeek := wed ;  
ThreeDaysLater := DayOfWeek + 3 ;
```

Exterior Algebra

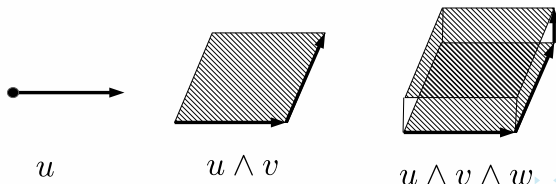
Grassmann's father: J. G. Grassmann



Hermann Grassmann
Wikipedia より引用

... the point is the original “producing” element;
from it through construction the line emerges..., if
we treat it (line) in the same manner as we
formerly treated the point, then the rectangle
emerges, ...

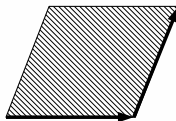
Justus G. Grassmann: “Raumlehre Theil”



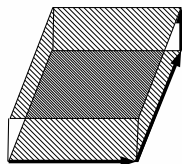
Vectors vs Rotors



1 vector



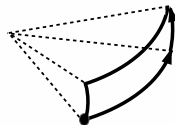
2 vector



3 vector



1 rotor



2 rotor

References

- Michael J. Crowe. A History of Vector Analysis: The Evolution of the Idea of a Vectorial System. Dover Reprints, 2015.
- Chris Doran, et al., In Advances in imaging and electron physics, volume 95, pp 271. Elsevier, 1996
- Chris Doran, et al., Geometric algebra for physicists. Cambridge University Press, 2003.
- David Hestenes. Journal of Mathematical Physics, 8(4): 1967.
- David Hestenes. Journal of Mathematical Physics, 16:556, 1975.
- David Hestenes. American Journal of Physics, 71(7):691, 2003.
- David Hestenes. Space-time algebra. Springer, 2015.
- Miroslav Josipovic. Geometric Multiplication of Vectors. Birkhaeuser, 2019.